MODELLING OF FULLERENE PRODUCTION BY THE ELECTRIC ARC-DISCHARGE METHOD Seminar

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Fullerenes

Fullerenes

What are fullerenes?

Fullerens are carbon forms that consist of a:

- spherical (buckyballs),
- ellipsoid, or
- cylindrical (buckytubes = nanotubes)

arrangement of carbon atoms.

Unique properties:

- chemical stability
- extreme strength
- can absorb light
- act as superconductors

Possible applications:

- medicine and electronics
- engineering and construction
- composites, paints, coatings
- aluminium, steel

Fullerenes

Buckyballs

Buckyballs

- Formed of pentagon and hexagon units of carbon
- Form hollow geodesic domes; bonding strains are equally distributed
- Most common: C₆₀





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Figure: Buckyballs C₆₀, C₇₀ and C₈₀ [1].

Fullerenes

Nanotubes

Single-wall carbon nanotubes (SWNT).

- type: closed, open
- graphene sheet rolled into a tube, caped with half a buckyball
- type: armchair (m = 1), zigzag (n = m), chirial



Figure: Single-wall nanotubes [3].

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Figure: SEM (left) and TEM (right) images of SWNT bundles [4].

Fullerenes

Nanotubes

Multi-wall carbon nanotubes (MWNT)

- multiple concentric or rolled graphene sheets
- type: Russian Doll model (concentric cylindres), Parchment model (a single sheet of graphene is rolled around itself)



Figure: Multi-wall nanotube [5].

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Figure: SEM (left) and TEM (right) images of MWNT bundles [4].

Fullerene production

Fullerene production

Production techniques

- Arc-discharge:
 - Arc vaporisation of 2 carbon rods placed a few mm apart.
 - SWNT, MWNT, buckyballs. Short tubes of random sizes in need of purification. The most efficient.
- Laser ablation (vaporisation):
 - Blast graphite with intense laser pulse.
 - Mostly MWNT, SWNT. Long tubes, MWNTs riddled with defects, diameter of SWNTs is controllable.
- Chemical vapour deposition (CVD):
 - A gas of carbon source is injected into an oven where heated substrate is present.
 - SWNT, Long bundles of tubes, good diameter control, few defects, costly.



Figure: 1. Arc-discharge apparatus [9]. 2. Laser ablation apparatus [7]. 3. CVD apparatus [8].

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Electric arc-discharge method

Arc-discharge cell

reactor tank with cooled walls



Figure: A scheme of a typical arc discharge reactor chamber and the locations where products are formed (Grlj, 2010).

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Models of fullerene growth

Models of fullerene growth

Fan (plasma) jet is formed as a consequence of heat and mass transfer.

Review of fullerene modelling:

- Kerstinin, Moravsky (1998): mathematical model combined with kinetics for fullerene formation
- Farhat et al. (2005): mathematical model based on carbon deposition on rotating cathode.
- Bilodeau et al. (1998): 2D model for the analysis of fullerene synthesis.
- Alekseev, Dyuzhev (1999): mathematical model connecting initial jet parameters and fullerene yield.



Figure: Fullerene formation scheme in arc discharge (Grlj, 2010).

Physical model

Assumptions

Physical model

Overview of the general assumptions:

- Steady state.
- Axisymmetric, laminar flow with Re < 10.
- Local thermodynamic equilibrium.

Bilodeau (1998):

- Uniform anode erosion rate over the electrode surface.
- Surface deposition on the cathode is governed by diffusion.
- Energy input in the arc is due to ohmic heating and to the enthalpy flux of electrons.
- ID electric field.

Farhat (2006):

- Radiation losses are accounted for by the net emission coefficient.
- Temperature dependent fluid properties.



Figure: The sketch of jet fan in arc-discharge reactor.

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Physical model

Governing equations including chemical reactions

Continuity equations

Continuity equation - general form:

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot (\rho \vec{u}) = S_m$$

2D steady state model (Bilodeau, 1998)

$$\vec{\nabla} \cdot (\rho \vec{u}) = S_m$$

Cylindrical coordinates:

$$\frac{\partial \rho}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (\rho r u_r) + \frac{\partial}{\partial z} (\rho u_z) = S_m$$

$$\frac{1}{r}\frac{\partial}{\partial r}(\rho r u_r) + \frac{\partial}{\partial z}(\rho u_z) = 0$$

1D stea (Farhat,	dy state 2006)	model	
$\frac{\partial \rho}{\partial t} = -$	$-\frac{u_z}{\rho}\frac{\partial\rho}{\partial z} -$	- 2V -	$\frac{\partial u_z}{\partial z} = 0$

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Physical model

Governing equations including chemical reactions

Momentum equations

Momentum equation - plasma - general form:

$$\frac{D(\rho \vec{u})}{Dt} = -\vec{\nabla}P + \vec{\nabla}^2(2\mu \vec{u}) + \vec{\nabla} \cdot (\mu \vec{\nabla} \times \vec{u}) + \rho \vec{g} + \vec{j} \times \vec{B} + \rho \vec{f}$$

Local thermodynamic equilibrium (L.T.E.)

Momentum equation - gas - general form:

$$\frac{\partial(\rho\vec{u})}{\partial t} + \vec{\nabla} \cdot (\rho\vec{u}\vec{u}) = -\vec{\nabla}P + \mu\vec{\nabla}^{2}\vec{u} + \rho\vec{g} + \vec{j}\times\vec{B} + \rho\vec{f}$$

Equation of state - general form:

$$P = \frac{\rho RT}{M}$$

Physical model

Governing equations including chemical reactions

Momentum equations 2

2D model (Bilodeau, 1998)

$$ec{
abla} \cdot (
ho ec{u} ec{u}) = -ec{
abla} P + \mu ec{
abla}^2 ec{u} +
ho ec{g} + ec{j} imes ec{B}$$

Radial momentum:

$$\rho\left(\frac{\partial u_r}{\partial t} + u_r\frac{\partial u_r}{\partial r} + u_z\frac{\partial u_r}{\partial z}\right) = -\frac{\partial P}{\partial r} + \mu\left(\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}(ru_r)\right) + \frac{\partial^2 u_r}{\partial z^2}\right) + \rho g_r - j_z B_\theta + \rho f_r$$

Axial momentum:

$$\rho\left(\frac{\partial u_z}{\partial t} + u_r\frac{\partial u_z}{\partial r} + u_z\frac{\partial u_z}{\partial z}\right) = -\frac{\partial P}{\partial z} + \mu\left(\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial u_z}{\partial r}\right) + \frac{\partial^2 u_z}{\partial z^2}\right) + \rho g_z + j_r B_\theta + \rho f_z$$

1D model (Farhat, 2006)

$$\rho \frac{\partial V}{\partial t} = -\frac{\partial}{\partial z} \left(\mu \frac{\partial V}{\partial z} \right) - \rho u_z \frac{\partial V}{\partial z} - \rho V^2 - \frac{1}{r} \frac{\partial P}{\partial r} = 0$$

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Physical model

Governing equations including chemical reactions

Conservation of species

Species conservation equation - general form:

$$\frac{\partial(\rho Y_i)}{\partial t} + \vec{\nabla} \cdot (\rho Y_i \vec{u}) = \vec{\nabla} \cdot (\rho D_i \vec{\nabla} Y_i) + S_{in}$$

2D steady state model (Bilodeau, 1998):

$$ec{
abla} \cdot (
ho ec{u} Y_C) = ec{
abla} \cdot (
ho D_C ec{
abla} Y_C) + S_{in}$$

1D steady state model (Farhat, 2006):

$$\rho \frac{\partial Y_i}{\partial t} + \frac{\partial (\rho Y_i V_i)}{\partial z} + \rho u \frac{\partial Y_i}{\partial z} = M_i \omega_i$$

Simplification:

$$\rho \frac{\partial Y_i}{\partial t} = M_i \omega_i$$

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Physical model

Governing equations including chemical reactions

Conservation of energy

The conservation of energy equation - general form:

$$\frac{D(\rho h)}{Dt} = \vec{\nabla} \cdot (k\vec{\nabla}T) + \frac{\vec{j}^2}{\sigma} + \frac{5}{2}\frac{k_B}{e}\vec{\nabla} \cdot (T\vec{j}) - (k - \rho D_C c_p)\vec{\nabla}(T_C - T_g) \cdot \vec{\nabla}Y_C - Q_{rad} - S_h$$

2D steady state model (Bilodeau, 1998):

$$\vec{\nabla} \cdot (\rho \vec{v} h) = \vec{\nabla} \cdot (k \vec{\nabla} T) + \frac{j_z^2}{\sigma} + \frac{5}{2} \frac{k_B}{e} c_p \vec{j} \cdot \vec{\nabla} T - (k - \rho D_C c_p) \vec{\nabla} (T_C - T_g) \cdot \vec{\nabla} Y_C - Q_{rad} + S_h$$

1D steady state model (Farhat, 2006):

$$\rho c_{p} \frac{\partial T}{\partial t} = \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) - \rho c_{p} u_{r} \frac{\partial T}{\partial z} - \sum_{i=1}^{n_{g}} \left(c_{pi} \rho Y_{i} V_{i} \frac{\partial T}{\partial r} + \omega_{i} h_{i} \right) + S_{h} - Q_{rad} = 0$$

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Physical model

Boundary and initial conditions

Boundary and initial conditions



Figure: Boundary and initial conditions (Bilodeau, 1998).

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Physical model

Boundary and initial conditions

Chemical kinetics model

Kinetic models for fullerene growth:

- intermediate cluster formation
- the pentagon road
- the fullerene road
- the ring road



Figure: Comparison of different fullerene growth models [6].

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Physical model

Boundary and initial conditions

Chemical kinetics model

The fullerene model:

$$k_{1,2r} = A_{1,2r} T^{\beta_{1,2r}} exp\left(-\frac{E_{1,2r}}{RT}\right)$$
$$q_r = k_{1r} \prod_{i=1}^{n_g} C_i^{\nu'_{ir}} - k_{2r} \prod_{i=1}^{n_g} C_i^{\nu''_{ir}}$$
$$\omega_i = \sum_{r=1}^R \nu_{ir} q_r = \frac{dC_i}{dt}$$

Chemistry of small clusters $C + C \leftrightarrow C_2$ $C + C_2 \leftrightarrow C_3$ $C_2 + C_2 \leftrightarrow C_3 + C_3$ Formation of carbon clusters CC $C_3 + C \leftrightarrow 0.100CC$ $C_3 + C_2 \leftrightarrow 0.125CC$ $C_3 + C_3 \leftrightarrow 0.150CC$ Growth of carbon clusters CC $CC + C \leftrightarrow 1.025CC$ $CC + C_2 \rightarrow 1.050CC$ $CC \rightarrow 0.95CC + C$ Formation of fullerene molecules C_{60}^F and C_{70}^F $CC + C_3 \rightarrow 0.70C_{60}^F$ $CC + C_2 \rightarrow 0.70C_{60}^F$ $CC + C \rightarrow 0.6833333C_{60}^{F}$ Decay of fullerene molecules C_{60}^F and C_{70}^F $C_{60F} \rightarrow 1.45CC + C_2$ $C_{70F} \rightarrow 1.70CC + C_2$ Formation of soot nuclei Z and growth of soot $CC + CC \rightarrow Z$ $Z + C_3 \rightarrow 1.0375Z$ $Z + C_2 \rightarrow 1.025Z$ $Z + C \rightarrow 1.0125Z$

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The model

The initial model

The initial model - domain scheme



Figure: 1D domain scheme.

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The initial model

The initial model

The initial model is based on 1D Farhat model (Farhat, 2006).

Continuity eq.:

$$\frac{\partial \rho}{\partial t} = -\frac{\partial}{\partial z} (\rho u_z) - 2V - \frac{\partial u_z}{\partial z} = 0$$

Momentum eq.:

$$\rho \frac{\partial u_r}{\partial t} = -\frac{\partial}{\partial z} \left(\mu \frac{\partial u_r}{\partial z} \right) - \rho u_z \frac{\partial u_r}{\partial z} - \frac{\partial p}{\partial r} - j_z B_\theta$$

Energy eq.:

$$\rho c_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial z} \left(k \frac{\partial T}{\partial z} \right) - \rho c_p u_r \frac{\partial T}{\partial z} - \sum_{i=1}^{n_g} \left(c_{pi} \rho Y_i V_i \frac{\partial T}{\partial r} + \omega_i h_i \right) + \frac{j_z^2}{\sigma} = 0$$

Species conservation eq.:

$$\rho \frac{\partial Y_i}{\partial t} = M_i \omega_i$$

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The model

The initial model

The initial model - boundary and initial conditions



Figure: Boundary and initial conditions for 1D model (Farhat, 2006).

The model

Planed improvements

The improved model - domain scheme



Figure: 2D domain scheme.

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The model

Planed improvements

Improved model

Initial model is going to be expanded to more dimensions (2D). Improved model is based on Bilodeau model (Bilodeau, 1998).

Continuity eq.:

$$\frac{\partial(\rho)}{\partial t} + \frac{1}{r}\frac{\partial}{\partial r}(\rho r u_r) + \frac{\partial}{\partial z}(\rho u_z) = S_m$$

Momentum eq.:

$$\rho\left(\frac{\partial u_r}{\partial t} + u_r\frac{\partial u_r}{\partial r} + u_z\frac{\partial u_r}{\partial z}\right) = -\frac{\partial p}{\partial r} + \mu\left(\frac{\partial}{\partial r}\left(\frac{1}{r}\frac{\partial}{\partial r}\left(ru_r\right)\right) + \frac{\partial^2 u_r}{\partial z^2}\right) + j_z B_\theta$$
$$\rho\left(\frac{\partial u_z}{\partial t} + u_r\frac{\partial u_z}{\partial r} + u_z\frac{\partial u_z}{\partial z}\right) = -\frac{\partial p}{\partial z} + \mu\left(\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial u_z}{\partial r}\right) + \frac{\partial^2 u_z}{\partial z^2}\right) + \rho g_z + j_r B_\theta$$

Energy eq.:

$$\frac{\partial(\rho h)}{\partial t} + \frac{1}{r}\frac{\partial}{\partial r}(r\rho u_r h) + \frac{\partial}{\partial z}(\rho u_z h) = \frac{1}{r}\frac{\partial}{\partial r}\left(rk\frac{\partial T}{\partial r}\right) + \frac{\partial}{\partial z}\left(k\frac{\partial T}{\partial z}\right) + \frac{j_z^2}{\sigma} + \frac{5}{2}\frac{k_b}{e}\left(j_r\frac{\partial T}{\partial r} + j_z\frac{\partial T}{\partial z}\right) - \frac{1}{r}\frac{\partial}{\partial r}(rk - r\rho D_C c_\rho)(T_C - T_g)\frac{\partial Y_C}{\partial r} - \frac{\partial}{\partial z}(k - \rho D_C c_\rho)(T_C - T_g)\frac{\partial Y_C}{\partial z}$$

Species conservation eq.:

$$\rho \frac{\partial Y_C}{\partial t} + \frac{1}{r} \frac{\partial}{\partial r} (r \rho u_r Y_C) + \frac{\partial}{\partial z} (\rho u_z Y_C) = \frac{1}{r} \frac{\partial}{\partial r} \left(r \rho u_r \frac{\partial Y_C}{\partial r} \right) + \frac{\partial}{\partial z} \left(\rho u_z \frac{\partial Y_C}{\partial z} \right) + S_{in}$$

The model

Planed improvements

The improved model - boundary and initial conditions



Figure: 2D boundary and initial conditions (Bilodeau, 1998).

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The model

Typical values of material properties

Values of reduced input parameters

Input parameters:

constant	label	value
anode diameter	2 <i>r</i> _A	6 - 7
cathode diameter	2r _C	6 - 16 mm
anode length	I _A	15-70 cm
cathode length	I _C	15 -30 cm
reactor length	$I_C + I_A + I_g$	39-100 cm
reactor diameter	2r	13.6-30 cm
current	1	60-100 A
pressure	Р	100-800 mbar
anode cathode distance	lg	1-12 mm
anode, cathode tip T	T_A	3300-3800 K
wall temperature	T_w	350 K
mass density of the gas	ρ	$9.24 \cdot 10^{-6} \frac{g}{cm^3}$
carbon mass fraction	n _C	$10^{-4} - 10^{-6}$
initial C mole fraction	N _C	$2.57 \cdot 10^{-4}$
initial C_2 mole fraction	N_{C_2}	0.583
current intensity	j	$3 \cdot 10^6 - 10^7 \frac{A}{m^2}$

The model

Typical values of material properties

Values of reduced output parameters

Output parameters:

constant	label	value
anode gas velocity	<i>u</i> _A	7818 <u>cm</u>
deposition rate		0.57 - 4.71 ^{mg} / _s
electric power dissipation	q	$1.24 \cdot 10^7 \frac{W}{m^2}$
dilution factor at the anode	au	20
erosion rate	Φ	$1.3 - 25 \cdot 10^{-3} \frac{g}{s}$
estimated electron density	N _e	$3.5 \cdot 10^{15} \frac{1}{cm^3}$
temperature	Т	350-17000 K
He number density	n _{He}	$1.4 \cdot 10^{18} \frac{1}{cm^3}$
Ni number density	n _{Ni}	$2.0 \cdot 10^{14} \frac{1}{cm^3}$
Y number density	ny	$3.2 \cdot 10^{14} \frac{1}{cm^3}$
growth rate	G	$1-1000rac{\mu m}{min}$

The model

Estimated parameter fields

Qualitative estimation of involved variables



Figure: Estimation of temperature field (Bilodeau, 1998).

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The model

Estimated parameter fields

Qualitative estimation of involved variables



Figure: Estimation of carbon mass fraction field (Bilodeau, 1998).

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The model

Estimated parameter fields

Qualitative estimation of involved variables



Figure: Estimation of axial current intensity field (Bilodeau, 1998).

The model

Estimated parameter fields

Estimated number of equations

Estimated number of equations calculated for a particular point for each time step (without boundary conditions):

• The initial model: 59 (Chemical reactions: 18 · 3, 5 governing equations)

• The improved model: 61 (Chemical reactions: 18 · 3, 7 governing equations)

Meshless method

Radial basis functions

Meshless method and radial basis functions

Meshless method = mesh reduction technique

A numerical simulation algorithm that uses a set of arbitrary nodes to represent the solution of a physical problem.

Radial basis functions (RBF)

General approximation functions of univariate polynomial splines to a multivariate domain.

$$\psi_i(\mathbf{r}) = \psi(\vec{p} - \vec{p}_i)$$

Commonly used RBFs:

- Gaussian (GA) $\psi(r) = e^{-(cr)^2}$
- multiquadric (MQ) $\psi(r) = \sqrt{r^2 + c^2}$

General form of an approximation function:

$$\Theta(ec{
ho}) = \sum_{i=1}^N lpha_i \psi_i(ec{
ho})$$

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Meshless method

Radial basis functions



Figure: Irregular domain discretized using (a) 3-noded triangular finite elements, b) boundary element, and (c) arbitrary interior and boundary points using a meshless method [10].

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Meshless method

Local RBF collocation method

Local radial basis function collocation method

Approximation function:

$$\Theta(\vec{p}) \approx \sum_{i=1}^{N} \alpha_i \psi_i(\vec{p})$$

Collocation condition:

$$\Theta(\vec{p}_i) = \theta_i$$

Linear system of N equations:

 $\mathbf{\Psi}\vec{\alpha}=\vec{\theta}$

PDE equations:

$$\frac{\partial^{i}}{\partial p_{\iota}^{i}} \Theta(\vec{p}) = \sum_{n=1}^{N} \alpha_{n} \frac{\partial^{i}}{\partial p_{\iota}^{i}} \Psi_{n}(\vec{p})$$

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Meshless method

Introduction of boundary conditions

Introduction of boundary conditions

Dirichlet

$$\Theta(\vec{p}) = \Theta_{BC} \quad \rightarrow \quad \Theta(\vec{p}) = \Theta_{BC}$$

Neuman

$$\frac{\partial}{\partial \vec{n}} \Theta(\vec{p}) = \Theta_{BC} \quad \rightarrow \quad \Theta_{BC} = \sum_{i=1}^{N} \alpha_i \frac{\partial}{\partial \vec{n}} \Psi_i(\vec{p})$$

Robin

$$\frac{\partial}{\partial \vec{n}} \Theta(\vec{p}) + b\Theta(\vec{p}) = \Theta_{BC} \quad \rightarrow \quad \Theta_{BC} = \sum_{i=1}^{N} \alpha_n \left(a \frac{\partial}{\partial \vec{n}} \Psi_i(\vec{p}) + b \Psi_i(\vec{p}) \right)$$

Conclusions

Conclusions

- Introduction to fullerene production and modelling.
- Presentation of arc discharge method.
- Formulation of a mathematical model.
- Description of a numerical method.

Future steps:

• Establishment of a minimal model (implement model, solution procedure)

• Comparison with measurements from actual cell

Bibliography and literature review

Literature review

More than 150 (154) articles were gathered on the subject of fullerene production and modelling. A comprehensive review of literature was done and is available at: https://4pm.cobik.si/projects/tabs/projectPortalTabDefFiles.jsf?list = 1&prjld = 1118

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Bibliography and literature review

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